

## ADAR1000 Phase Error Definitions

Phase Error:

$$Phase\ Error = Phase_{Measured} - Phase_{Ideal}$$

Peak Error:

$$Peak\ Phase\ Error = Max(abs(\{Phase\ Error_i\}))$$

Where  $\{Phase\ Error_i\}$  is a set of phase errors between the 0 and 360 degree phase settings, in 2.8125 degree steps.

Average Phase Error:

$$Average\ Phase\ Error = \frac{1}{128} \sum_{i=1}^{128} Phase\ Error_i$$

RMS Phase Error (standard), not shown in the datasheet:

$$RMS\ Phase\ Error = \sqrt{\frac{1}{128} \sum_{i=1}^{128} (Phase\ Error_i)^2}$$

RMS Phase Error (referenced to Average Phase Error) shown in datasheet:

$$RMS\ Phase\ Error\ (ref:\ Average\ Error) = \sqrt{\frac{1}{128} \sum_{i=1}^{128} (RMS\ Phase\ Error_i - Average\ Error)^2}$$

Notes:

- Rx Phase error is referenced to phase setting 202.5 degrees, e.g.  $Phase_{Measured\_202.5} = Phase_{Ideal\_202.5} = 202.5$  degrees (normalized), thus Phase Error at this setting is defined as zero.
- Tx Phase error is referenced to phase setting 22.5 degrees, e.g.  $Phase_{Measured\_22.5} = Phase_{Ideal\_22.5} = 22.5$  degrees (normalized), thus Phase Error at this setting is defined as zero.
- Errors are calculated at each frequency point